# **Nagios Object Definitions**

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## **Host Definition**

#### **Definition Format**

Note: Directives followed by a \* are required.

define host{	
host_name*	host_name
alias*	alias
display_name	display_name
address*	address
parents	host_names
hostgroups	hostgroup_names
check_command	command_name
initial_state	[o,d,u]
max_check_attempts*	#
check_interval	#
retry_interval	#
active_checks_enabled	[0/1]
passive_checks_enabled	[0/1]
check_period*	timeperiod_name
obsess_over_host	[0/1]
check_freshness	[0/1]
freshness_threshold	#
event_handler	command_name
event_handler_enabled	[0/1]
low_flap_threshold	#
high_flap_threshold	#
flap_detection_enabled	[0/1]
flap_detection_options	[o,d,u]
process_perf_data	[0/1]
retain_status_information	[0/1]

[0/1]
contacts
contact_groups
#
#
timeperiod_name
[d,u,r,f,s]
[0/1]
[o,d,u]
note_string
url
url
image_file
alt_string
image_file
image_file
$x\_coord,y\_coord$
x_coord,y_coord,z_coord

define host{	
host name	bogus-router
alias	Bogus Router #1
address	192.168.1.254
parents	server-backbone
check_command	check-host-alive
check_interval	5
retry_interval	1
max_check_attempts	5
check_period	24x7
process_perf_data	0
retain_nonstatus_information	0
contact_groups	router-admins
notification_interval	30
notification_period	24x7
notification_options	d,u,r
}	

host_name	This directive is used to define a short name used to identify the host. It is used in host group and service definitions to reference this particular host. Hosts can have multiple services (which are monitored) associated with them. When used properly, the \$HOSTNAME\$ macro will contain this short name.
alias	This directive is used to define a longer name or description used to identify the host. It is provided in order to allow you to more easily identify a particular host. When used properly, the \$HOSTALIAS\$ macro will contain this alias/description.
address	This directive is used to define the address of the host. Normally, this is an IP address, although it could really be anything you want (so long as it can be used to check the status of the host). You can use a FQDN to identify the host instead of an IP address, but if DNS services are not 3333cc le this could cause problems. When used properly, the \$HOSTADDRESS\$ macro will contain this address. <b>Note:</b> If you do not specify an

	address directive in a host definition, the name of the host will be used as its address. A word of caution about doing this, however - if DNS fails, most of your service checks will fail because the plugins will be unable to resolve the host name.
display_name	This directive is used to define an alternate name that should be displayed in the web interface for this host. If not specified, this defaults to the value you specify for the <i>host_name</i> directive. Note: The current CGIs do not use this option, although future versions of the web interface will.
parents	This directive is used to define a comma-delimited list of short names of the "parent" hosts for this particular host. Parent hosts are typically routers, switches, firewalls, etc. that lie between the monitoring host and a remote hosts. A router, switch, etc. which is closest to the remote host is considered to be that host's "parent". Read the "Determining Status and Reachability of Network Hosts" document located here for more information. If this host is on the same network segment as the host doing the monitoring (without any intermediate routers, etc.) the host is considered to be on the local network and will not have a parent host. Leave this value blank if the host does not have a parent host (i.e. it is on the same segment as the Nagios host). The order in which you specify parent hosts has no effect on how things are monitored.
hostgroups	This directive is used to identify the <i>short name(s)</i> of the <u>hostgroup(s)</u> that the host belongs to. Multiple hostgroups should be separated by commas. This directive may be used as an alternative to (or in addition to) using the <i>members</i> directive in <u>hostgroup</u> definitions.
check_command	This directive is used to specify the <i>short name</i> of the <u>command</u> that should be used to check if the host is up or down. Typically, this command would try and ping the host to see if it is "alive". The command must return a status of OK (0) or Nagios will assume the host is down. If you leave this argument blank, the host will <i>not</i> be actively checked. Thus, Nagios will likely always assume the host is up (it may show up as being in a "PENDING" state in the web interface). This is useful if you are monitoring printers or other devices that are frequently turned off. The maximum amount of time that the notification command can run is controlled by the <u>host_check_timeout</u> option.
initial_state	By default Nagios will assume that all hosts are in UP states when it starts. You can override the initial state for a host by using this directive. Valid options are: $\mathbf{o} = UP$ , $\mathbf{d} = DOWN$ , and $\mathbf{u} = UNREACHABLE$ .
max_check_attempts	This directive is used to define the number of times that Nagios will retry the host check command if it returns any state other than an OK state. Setting this value to 1 will cause Nagios to generate an alert without retrying the host check. Note: If you do not want to check the status of the host, you must still set this to a minimum value of 1. To bypass the host check, just leave the <i>check_command</i> option blank.
check_interval	This directive is used to define the number of "time units" between regularly scheduled checks of the host. Unless you've changed the <u>interval_length</u> directive from the default value of 60, this number will mean minutes. More information on this value can be found in the <u>check scheduling</u> documentation.
retry_interval	This directive is used to define the number of "time units" to wait before scheduling a re-check of the hosts. Hosts are rescheduled at the retry interval when they have changed to a non-UP state. Once the host has been retried <b>max_check_attempts</b> times without a change in its status, it will revert to being scheduled at its "normal" rate as defined by the <b>check_interval</b> value. Unless you've changed the <u>interval_length</u> directive from the default value of 60, this number will mean minutes. More information on this value can be found in the <u>check scheduling</u> documentation.
active_checks_enabled	This directive is used to determine whether or not active checks (either regularly scheduled or on-demand) of this host are enabled. Values: $0 =$ disable active host checks, $1 =$ enable active host checks (default).
passive_checks_enabled	This directive is used to determine whether or not passive checks are enabled for this host. Values: $0 =$ disable passive host checks, $1 =$ enable passive host checks (default).
check_period	This directive is used to specify the short name of the <u>time period</u> during which active checks of this host can be made.

obsess_over_host	This directive determines whether or not checks for the host will be "obsessed" over using the <u>ochp_command</u> .
check_freshness	This directive is used to determine whether or not <u>freshness checks</u> are enabled for this host. Values: $0 =$ disable freshness checks, $1 =$ enable freshness checks (default).
freshness_threshold	This directive is used to specify the freshness threshold (in seconds) for this host. If you set this directive to a value of 0, Nagios will determine a freshness threshold to use automatically.
event_handler	This directive is used to specify the <i>short name</i> of the <u>command</u> that should be run whenever a change in the state of the host is detected (i.e. whenever it goes down or recovers). Read the documentation on <u>event handlers</u> for a more detailed explanation of how to write scripts for handling events. The maximum amount of time that the event handler command can run is controlled by the <u>event handler_timeout</u> option.
event_handler_enabled	This directive is used to determine whether or not the event handler for this host is enabled. Values: $0 =$ disable host event handler, $1 =$ enable host event handler.
low_flap_threshold	This directive is used to specify the low state change threshold used in flap detection for this host. More information on flap detection can be found <u>here</u> . If you set this directive to a value of 0, the program-wide value specified by the <u>low_host_flap_threshold</u> directive will be used.
high_flap_threshold	This directive is used to specify the high state change threshold used in flap detection for this host. More information on flap detection can be found <u>here</u> . If you set this directive to a value of 0, the program-wide value specified by the <u>high_host_flap_threshold</u> directive will be used.
flap_detection_enabled	This directive is used to determine whether or not flap detection is enabled for this host. More information on flap detection can be found <u>here</u> . Values: $0 =$ disable host flap detection, $1 =$ enable host flap detection.
flap_detection_options	This directive is used to determine what host states the <u>flap detection logic</u> will use for this host. Valid options are a combination of one or more of the following: $\mathbf{o} = UP$ states, $\mathbf{d} = DOWN$ states, $\mathbf{u} = UNREACHABLE$ states.
process_perf_data	This directive is used to determine whether or not the processing of performance data is enabled for this host. Values: $0 =$ disable performance data processing, $1 =$ enable performance data processing.
retain_status_information	This directive is used to determine whether or not status-related information about the host is retained across program restarts. This is only useful if you have enabled state retention using the <u>retain_state_information</u> directive. Value: $0 =$ disable status information retention, $1 =$ enable status information retention.
retain_nonstatus_information	This directive is used to determine whether or not non-status information about the host is retained across program restarts. This is only useful if you have enabled state retention using the <u>retain_state_information</u> directive. Value: $0 =$ disable non-status information retention, $1 =$ enable non-status information retention.
contacts	This is a list of the <i>short names</i> of the <u>contacts</u> that should be notified whenever there are problems (or recoveries) with this host. Multiple contacts should be separated by commas. Useful if you want notifications to go to just a few people and don't want to configure <u>contact groups</u> . You must specify at least one contact or contact group in each host definition.
contact_groups	This is a list of the <i>short names</i> of the <u>contact groups</u> that should be notified whenever there are problems (or recoveries) with this host. Multiple contact groups should be separated by commas. You must specify at least one contact or contact group in each host definition.
notification_interval	This directive is used to define the number of "time units" to wait before re-notifying a contact that this service is <i>still</i> down or unreachable. Unless you've changed the <u>interval_length</u> directive from the default value of 60, this number will mean minutes. If you set this value to 0, Nagios will <i>not</i> re-notify contacts about problems for this host - only one problem notification will be sent out.
first_notification_delay	This directive is used to define the number of "time units" to wait before sending out

	the first problem notification when this host enters a non-UP state. Unless you've changed the <u>interval_length</u> directive from the default value of 60, this number will mean minutes. If you set this value to 0, Nagios will start sending out notifications immediately.
notification_period	This directive is used to specify the short name of the <u>time period</u> during which notifications of events for this host can be sent out to contacts. If a host goes down, becomes unreachable, or recoveries during a time which is not covered by the time period, no notifications will be sent out.
notification_options	This directive is used to determine when notifications for the host should be sent out. Valid options are a combination of one or more of the following: $\mathbf{d}$ = send notifications on a DOWN state, $\mathbf{u}$ = send notifications on an UNREACHABLE state, $\mathbf{r}$ = send notifications on recoveries (OK state), $\mathbf{f}$ = send notifications when the host starts and stops <u>flapping</u> , and $\mathbf{s}$ = send notifications when <u>scheduled downtime</u> starts and ends. If you specify $\mathbf{n}$ (none) as an option, no host notifications will be sent out. If you do not specify any notification options, Nagios will assume that you want notifications to be sent out for all possible states. Example: If you specify $\mathbf{d}$ , $\mathbf{r}$ in this field, notifications will only be sent out when the host goes DOWN and when it recovers from a DOWN state.
notifications_enabled	This directive is used to determine whether or not notifications for this host are enabled. Values: $0 =$ disable host notifications, $1 =$ enable host notifications.
stalking_options	This directive determines which host states "stalking" is enabled for. Valid options are a combination of one or more of the following: $\mathbf{o} = \text{stalk}$ on UP states, $\mathbf{d} = \text{stalk}$ on DOWN states, and $\mathbf{u} = \text{stalk}$ on UNREACHABLE states. More information on state stalking can be found <u>here</u> .
notes	This directive is used to define an optional string of notes pertaining to the host. If you specify a note here, you will see the it in the <u>extended information</u> CGI (when you are viewing information about the specified host).
notes_url	This variable is used to define an optional URL that can be used to provide more information about the host. If you specify an URL, you will see a red folder icon in the CGIs (when you are viewing host information) that links to the URL you specify here. Any valid URL can be used. If you plan on using relative paths, the base path will the the same as what is used to access the CGIs (i.e. <i>/cgi-bin/nagios/</i> ). This can be very useful if you want to make detailed information on the host, emergency contact methods, etc. available to other support staff.
action_url	This directive is used to define an optional URL that can be used to provide more actions to be performed on the host. If you specify an URL, you will see a red "splat" icon in the CGIs (when you are viewing host information) that links to the URL you specify here. Any valid URL can be used. If you plan on using relative paths, the base path will the the same as what is used to access the CGIs (i.e. <i>/cgi-bin/nagios/</i> ).
icon_image	This variable is used to define the name of a GIF, PNG, or JPG image that should be associated with this host. This image will be displayed in the various places in the CGIs. The image will look best if it is 40x40 pixels in size. Images for hosts are assumed to be in the <b>logos</b> / subdirectory in your HTML images directory (i.e. /usr/local/nagios/share/images/logos).
icon_image_alt	This variable is used to define an optional string that is used in the ALT tag of the image specified by the <i><icon_image></icon_image></i> argument.
vrml_image	This variable is used to define the name of a GIF, PNG, or JPG image that should be associated with this host. This image will be used as the texture map for the specified host in the <u>statuswrl</u> CGI. Unlike the image you use for the <i><icon_image></icon_image></i> variable, this one should probably <i>not</i> have any transparency. If it does, the host object will look a bit wierd. Images for hosts are assumed to be in the <b>logos</b> / subdirectory in your HTML images directory (i.e. <i>/usr/local/nagios/share/images/logos</i> ).
statusmap_image	This variable is used to define the name of an image that should be associated with this host in the <u>statusmap</u> CGI. You can specify a JPEG, PNG, and GIF image if you want, although I would strongly suggest using a GD2 format image, as other image formats

	will result in a lot of wasted CPU time when the statusmap image is generated. GD2 images can be created from PNG images by using the <b>pngtogd2</b> utility supplied with Thomas Boutell's <u>gd library</u> . The GD2 images should be created in <i>uncompressed</i> format in order to minimize CPU load when the statusmap CGI is generating the network map image. The image will look best if it is 40x40 pixels in size. You can leave these option blank if you are not using the statusmap CGI. Images for hosts are assumed to be in the <b>logos</b> / subdirectory in your HTML images directory (i.e. <i>/usr/local/nagios/share/images/logos</i> ).
2d_coords	This variable is used to define coordinates to use when drawing the host in the statusmap CGI. Coordinates should be given in positive integers, as they correspond to physical pixels in the generated image. The origin for drawing (0,0) is in the upper left hand corner of the image and extends in the positive x direction (to the right) along the top of the image and in the positive y direction (down) along the left hand side of the image. For reference, the size of the icons drawn is usually about 40x40 pixels (text takes a little extra space). The coordinates you specify here are for the upper left hand corner of the host icon that is drawn. Note: Don't worry about what the maximum x and y coordinates that you can use are. The CGI will automatically calculate the maximum dimensions of the image it creates based on the largest x and y coordinates you specify.
3d_coords	This variable is used to define coordinates to use when drawing the host in the <u>statuswrl</u> CGI. Coordinates can be positive or negative real numbers. The origin for drawing is (0.0,0.0,0.0). For reference, the size of the host cubes drawn is 0.5 units on each side (text takes a little more space). The coordinates you specify here are used as the center of the host cube.

# Host Group Definition

#### **Definition Format**

Note: Directives followed by a \* are required.

define hostgroup{	
hostgroup_name*	hostgroup_name
alias*	alias
members	hosts
hostgroup_members	hostgroups
notes	note_string
notes_url	url
action_url	url
}	

#### Example Definition

define hostgroup{	
hostgroup_name	novell-servers
alias	Novell Servers
members	netware1,netware2,netware3,netware4
}	

hostgroup_name	This directive is used to define a short name used to identify the host group.
alias	This directive is used to define is a longer name or description used to identify the host group. It is provided in order to allow you to more easily identify a particular host group.
members	This is a list of the <i>short names</i> of <u>hosts</u> that should be included in this group. Multiple host names should be separated by commas. This directive may be used as an alternative to (or in

	addition to) the hostgroups directive in host definitions.
hostgroup_members	This optional directive can be used to include hosts from other "sub" host groups in this host group. Specify a comma-delimited list of short names of other host groups whose members should be included in this group.
notes	This directive is used to define an optional string of notes pertaining to the host. If you specify a note here, you will see the it in the <u>extended information</u> CGI (when you are viewing information about the specified host).
notes_url	This variable is used to define an optional URL that can be used to provide more information about the host group. If you specify an URL, you will see a red folder icon in the CGIs (when you are viewing hostgroup information) that links to the URL you specify here. Any valid URL can be used. If you plan on using relative paths, the base path will the the same as what is used to access the CGIs (i.e. <i>/cgi-bin/nagios/</i> ). This can be very useful if you want to make detailed information on the host group, emergency contact methods, etc. available to other support staff.
action_url	This directive is used to define an optional URL that can be used to provide more actions to be performed on the host group. If you specify an URL, you will see a red "splat" icon in the CGIs (when you are viewing hostgroup information) that links to the URL you specify here. Any valid URL can be used. If you plan on using relative paths, the base path will the the same as what is used to access the CGIs (i.e. <i>/cgi-bin/nagios/</i> ).

#### **Service Definition**

#### **Definition Format**

Note: Directives followed by a \* are required. define service{ host\_name\* host\_name hostgroup\_name hostgroup name service\_description\* service description display name display name servicegroups servicegroup names is volatile [0/1] check command\* command name initial\_state [0,w,u,c]max\_check\_attempts\* # check\_interval\* # retry\_interval\* # [0/1] active checks enabled passive checks enabled [0/1] check period\* timeperiod\_name obsess over service [0/1] check\_freshness [0/1]freshness\_threshold # event\_handler command name event\_handler\_enabled [0/1] low\_flap\_threshold # high flap threshold # flap detection enabled [0/1] flap\_detection\_options [0,w,c,u]process\_perf\_data [0/1]retain\_status\_information [0/1]7

retain_nonstatus_information	[0/1]
notification_interval*	#
first_notification_delay	#
notification_period*	timeperiod_name
notification_options	[w,u,c,r,f,s]
notifications_enabled	[0/1]
contacts*	contacts
contact_groups*	contact_groups
stalking_options	[o,w,u,c]
notes	note_string
notes_url	url
action_url	url
icon_image	image_file
icon_image_alt	alt_string
}	

define service{	
host name	linux-server
service descriptio	on check-disk-sdal
check command	check-disk!/dev/sda1
max check attempts	5
check interval 5	
retry interval 3	
check period	24x7
notification inter	rval 30
notification_perio	od 24x7
notification optic	ons w,c,r
contact groups	linux-admins
} —	

host_name	This directive is used to specify the <i>short name(s)</i> of the <u>host(s)</u> that the service "runs" on or is associated with. Multiple hosts should be separated by commas.
hostgroup_name	This directive is used to specify the <i>short name(s)</i> of the <u>hostgroup(s)</u> that the service "runs" on or is associated with. Multiple hostgroups should be separated by commas. The hostgroup_name may be used instead of, or in addition to, the host_name directive.
service_description	This directive is used to define the description of the service, which may contain spaces, dashes, and colons (semicolons, apostrophes, and quotation marks should be avoided). No two services associated with the same host can have the same description. Services are uniquely identified with their <i>host_name</i> and <i>service_description</i> directives.
display_name	This directive is used to define an alternate name that should be displayed in the web interface for this service. If not specified, this defaults to the value you specify for the <i>service_description</i> directive. Note: The current CGIs do not use this option, although future versions of the web interface will.
servicegroups	This directive is used to identify the <i>short name(s)</i> of the <u>servicegroup(s)</u> that the service belongs to. Multiple servicegroups should be separated by commas. This directive may be used as an alternative to using the <i>members</i> directive in <u>servicegroup</u> definitions.
is_volatile	This directive is used to denote whether the service is "volatile". Services are normally <i>not</i> volatile. More information on volatile service and how they differ from normal services can be found <u>here</u> . Value: $0 =$ service is not volatile, $1 =$ service is volatile.

check_command	This directive is used to specify the <i>short name</i> of the <u>command</u> that Nagios will run in order to check the status of the service. The maximum amount of time that the service check command can run is controlled by the <u>service_check_timeout</u> option.
initial_state	By default Nagios will assume that all services are in OK states when it starts. You can override the initial state for a service by using this directive. Valid options are: $\mathbf{o} = OK$ , $\mathbf{w} = WARNING$ , $\mathbf{u} = UNKNOWN$ , and $\mathbf{c} = CRITICAL$ .
max_check_attempts	This directive is used to define the number of times that Nagios will retry the service check command if it returns any state other than an OK state. Setting this value to 1 will cause Nagios to generate an alert without retrying the service check again.
check_interval	This directive is used to define the number of "time units" to wait before scheduling the next "regular" check of the service. "Regular" checks are those that occur when the service is in an OK state or when the service is in a non-OK state, but has already been rechecked <b>max_check_attempts</b> number of times. Unless you've changed the <u>interval_length</u> directive from the default value of 60, this number will mean minutes. More information on this value can be found in the <u>check scheduling</u> documentation.
retry_interval	This directive is used to define the number of "time units" to wait before scheduling a re- check of the service. Services are rescheduled at the retry interval when they have changed to a non-OK state. Once the service has been retried <b>max_check_attempts</b> times without a change in its status, it will revert to being scheduled at its "normal" rate as defined by the <b>check_interval</b> value. Unless you've changed the <u>interval_length_</u> directive from the default value of 60, this number will mean minutes. More information on this value can be found in the <u>check scheduling</u> documentation.
active_checks_enabled	This directive is used to determine whether or not active checks of this service are enabled. Values: $0 =$ disable active service checks, $1 =$ enable active service checks (default).
passive_checks_enabled	This directive is used to determine whether or not passive checks of this service are enabled. Values: $0 =$ disable passive service checks, $1 =$ enable passive service checks (default).
check_period	This directive is used to specify the short name of the <u>time period</u> during which active checks of this service can be made.
obsess_over_service	This directive determines whether or not checks for the service will be "obsessed" over using the <u>ocsp_command</u> .
check_freshness	This directive is used to determine whether or not <u>freshness checks</u> are enabled for this service. Values: $0 =$ disable freshness checks, $1 =$ enable freshness checks (default).
freshness_threshold	This directive is used to specify the freshness threshold (in seconds) for this service. If you set this directive to a value of 0, Nagios will determine a freshness threshold to use automatically.
event_handler	This directive is used to specify the <i>short name</i> of the <u>command</u> that should be run whenever a change in the state of the service is detected (i.e. whenever it goes down or recovers). Read the documentation on <u>event handlers</u> for a more detailed explanation of how to write scripts for handling events. The maximum amount of time that the event handler command can run is controlled by the <u>event_handler_timeout</u> option.
event_handler_enabled	This directive is used to determine whether or not the event handler for this service is enabled. Values: $0 =$ disable service event handler, $1 =$ enable service event handler.
low_flap_threshold	This directive is used to specify the low state change threshold used in flap detection for this service. More information on flap detection can be found <u>here</u> . If you set this directive to a value of 0, the program-wide value specified by the <u>low_service_flap_threshold</u> directive will be used.
high_flap_threshold	This directive is used to specify the high state change threshold used in flap detection for this service. More information on flap detection can be found <u>here</u> . If you set this directive to a value of 0, the program-wide value specified by the <u>high_service_flap_threshold</u> directive will be used.
flap_detection_enabled	This directive is used to determine whether or not flap detection is enabled for this

	service. More information on flap detection can be found <u>here</u> . Values: $0 =$ disable service flap detection, $1 =$ enable service flap detection.
flap_detection_options	This directive is used to determine what service states the <u>flap detection logic</u> will use for this service. Valid options are a combination of one or more of the following: $\mathbf{o} = OK$ states, $\mathbf{w} = WARNING$ states, $\mathbf{c} = CRITICAL$ states, $\mathbf{u} = UNKNOWN$ states.
process_perf_data	This directive is used to determine whether or not the processing of performance data is enabled for this service. Values: $0 =$ disable performance data processing, $1 =$ enable performance data processing.
retain_status_information	This directive is used to determine whether or not status-related information about the service is retained across program restarts. This is only useful if you have enabled state retention using the <u>retain_state_information</u> directive. Value: 0 = disable status information retention, 1 = enable status information retention.
retain_nonstatus_information	This directive is used to determine whether or not non-status information about the service is retained across program restarts. This is only useful if you have enabled state retention using the <u>retain_state_information</u> directive. Value: 0 = disable non-status information retention.
notification_interval	This directive is used to define the number of "time units" to wait before re-notifying a contact that this service is <i>still</i> in a non-OK state. Unless you've changed the <u>interval_length</u> directive from the default value of 60, this number will mean minutes. If you set this value to 0, Nagios will <i>not</i> re-notify contacts about problems for this service - only one problem notification will be sent out.
first_notification_delay	This directive is used to define the number of "time units" to wait before sending out the first problem notification when this service enters a non-OK state. Unless you've changed the <u>interval_length</u> directive from the default value of 60, this number will mean minutes. If you set this value to 0, Nagios will start sending out notifications immediately.
notification_period	This directive is used to specify the short name of the <u>time period</u> during which notifications of events for this service can be sent out to contacts. No service notifications will be sent out during times which is not covered by the time period.
notification_options	This directive is used to determine when notifications for the service should be sent out. Valid options are a combination of one or more of the following: $\mathbf{w} =$ send notifications on a WARNING state, $\mathbf{u} =$ send notifications on an UNKNOWN state, $\mathbf{c} =$ send notifications on a CRITICAL state, $\mathbf{r} =$ send notifications on recoveries (OK state), $\mathbf{f} =$ send notifications when the service starts and stops <u>flapping</u> , and $\mathbf{s} =$ send notifications when <u>scheduled downtime</u> starts and ends. If you specify $\mathbf{n}$ (none) as an option, no service notifications will be sent out. If you do not specify any notification options, Nagios will assume that you want notifications to be sent out for all possible states. Example: If you specify $\mathbf{w}, \mathbf{r}$ in this field, notifications will only be sent out when the service goes into a WARNING state and when it recovers from a WARNING state.
notifications_enabled	This directive is used to determine whether or not notifications for this service are enabled. Values: $0 =$ disable service notifications, $1 =$ enable service notifications.
contacts	This is a list of the <i>short names</i> of the <u>contacts</u> that should be notified whenever there are problems (or recoveries) with this service. Multiple contacts should be separated by commas. Useful if you want notifications to go to just a few people and don't want to configure <u>contact groups</u> . You must specify at least one contact or contact group in each service definition.
contact_groups	This is a list of the <i>short names</i> of the <u>contact groups</u> that should be notified whenever there are problems (or recoveries) with this service. Multiple contact groups should be separated by commas. You must specify at least one contact or contact group in each service definition.
stalking_options	This directive determines which service states "stalking" is enabled for. Valid options are a combination of one or more of the following: $\mathbf{o} = \text{stalk}$ on OK states, $\mathbf{w} = \text{stalk}$ on WARNING states, $\mathbf{u} = \text{stalk}$ on UNKNOWN states, and $\mathbf{c} = \text{stalk}$ on CRITICAL states. More information on state stalking can be found <u>here</u> .

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notes	This directive is used to define an optional string of notes pertaining to the service. If you specify a note here, you will see the it in the <u>extended information</u> CGI (when you are viewing information about the specified service).
notes_url	This directive is used to define an optional URL that can be used to provide more information about the service. If you specify an URL, you will see a red folder icon in the CGIs (when you are viewing service information) that links to the URL you specify here. Any valid URL can be used. If you plan on using relative paths, the base path will the the same as what is used to access the CGIs (i.e. <i>/cgi-bin/nagios/</i> ). This can be very useful if you want to make detailed information on the service, emergency contact methods, etc. available to other support staff.
action_url	This directive is used to define an optional URL that can be used to provide more actions to be performed on the service. If you specify an URL, you will see a red "splat" icon in the CGIs (when you are viewing service information) that links to the URL you specify here. Any valid URL can be used. If you plan on using relative paths, the base path will the the same as what is used to access the CGIs (i.e. <i>/cgi-bin/nagios/</i> ).
icon_image	This variable is used to define the name of a GIF, PNG, or JPG image that should be associated with this service. This image will be displayed in the <u>status</u> and <u>extended</u> <u>information</u> CGIs. The image will look best if it is 40x40 pixels in size. Images for services are assumed to be in the <b>logos</b> / subdirectory in your HTML images directory (i.e. <i>/usr/local/nagios/share/images/logos</i> ).
icon_image_alt	This variable is used to define an optional string that is used in the ALT tag of the image specified by the <i><icon_image></icon_image></i> argument. The ALT tag is used in the <u>status</u> , <u>extended</u> <u>information</u> and <u>statusmap</u> CGIs.

## **Service Group Definition**

#### **Definition Format**

Note: Directives followed by a \* are required.

define servicegroup{	
servicegroup_name*	servicegroup_name
alias*	alias
members	services
servicegroup_members	servicegroups
notes	note_string
notes_url	url
action_url	url
}	

### Example Definition

define servicegroup{	
servicegroup_name	dbservices
alias	Database Services
members	<pre>ms1,SQL Server,ms1,SQL Server Agent,ms1,SQL DTC</pre>
}	

servicegroup_nam e	This directive is used to define a short name used to identify the service group.
	This directive is used to define is a longer name or description used to identify the service group. It is provided in order to allow you to more easily identify a particular service group.

members	This is a list of the <i>descriptions</i> of <u>services</u> (and the names of their corresponding hosts) that should be included in this group. Host and service names should be separated by commas. This directive may be used as an alternative to the <i>servicegroups</i> directive in <u>service definitions</u> . The format of the member directive is as follows (note that a host name must precede a service name/description): members= <host1>,<service1>,<host2>,<service2>,,<hostn>,<servicen></servicen></hostn></service2></host2></service1></host1>
servicegroup_members	This optional directive can be used to include services from other "sub" service groups in this service group. Specify a comma-delimited list of short names of other service groups whose members should be included in this group.
notes	This directive is used to define an optional string of notes pertaining to the service group. If you specify a note here, you will see the it in the <u>extended information</u> CGI (when you are viewing information about the specified service group).
notes_url	This directive is used to define an optional URL that can be used to provide more information about the service group. If you specify an URL, you will see a red folder icon in the CGIs (when you are viewing service group information) that links to the URL you specify here. Any valid URL can be used. If you plan on using relative paths, the base path will the the same as what is used to access the CGIs (i.e. <i>/cgi-bin/nagios/</i> ). This can be very useful if you want to make detailed information on the service group, emergency contact methods, etc. available to other support staff.
action_url	This directive is used to define an optional URL that can be used to provide more actions to be performed on the service group. If you specify an URL, you will see a red "splat" icon in the CGIs (when you are viewing service group information) that links to the URL you specify here. Any valid URL can be used. If you plan on using relative paths, the base path will the the same as what is used to access the CGIs (i.e. /cgi-bin/nagios/).

## **Contact Definition**

#### **Definition Format**

Note: Directives followed by a \* are required.

define contact{	
contact_name*	contact_name
alias	alias
contactgroups	contactgroup_names
host_notifications_enabled*	[0/1]
service_notifications_enabled*	[0/1]
host_notification_period*	timeperiod_name
service_notification_period*	timeperiod_name
host_notification_options*	[d,u,r,f,s,n]
service_notification_options*	[w,u,c,r,f,s,n]
host_notification_commands*	command_name
service_notification_commands*	command_name
email	email_address
pager	pager_number or pager_email_gateway
addressx	additional_contact_address
can_submit_commands	[0/1]
retain_status_information	[0/1]
retain_nonstatus_information	[0/1]
}	

define	contact{			
	contact_name		jdoe	
	alias		John Doe	
	host_notifications_enab	led	1	
	service_notifications_e	nabled	1	
	service_notification_pe	riod	24x7	
	host_notification_perio	d	24x7	
	service notification op	tions	w,u,C,r	
	host_notification_optio	ns	d,u,r	
	service_notification_co	mmands	notify-by-email	
	host_notification_comma	nds	host-notify-by-email	
	emailjdoe@loc		calhost.localdomain	
pager 555-		555-555	555@pagergateway.localhost.localdomain	
	address1		xxxxx.xyyy@icq.com	
	address2		555-555-5555	
	can submit commands	1		
	}			

contact_name	This directive is used to define a short name used to identify the contact. It is referenced in <u>contact group</u> definitions. Under the right circumstances, the \$CONTACTNAME\$ <u>macro</u> will contain this value.
alias	This directive is used to define a longer name or description for the contact. Under the rights circumstances, the \$CONTACTALIAS\$ <u>macro</u> will contain this value. If not specified, the <i>contact_name</i> will be used as the alias.
contactgroups	This directive is used to identify the <i>short name(s)</i> of the <u>contactgroup(s)</u> that the contact belongs to. Multiple contactgroups should be separated by commas. This directive may be used as an alternative to (or in addition to) using the <i>members</i> directive in <u>contactgroup</u> definitions.
host_notifications_enabled	This directive is used to determine whether or not the contact will receive notifications about host problems and recoveries. Values: $0 = \text{don't send notifications}$ , $1 = \text{send notifications}$ .
service_notifications_enabled	This directive is used to determine whether or not the contact will receive notifications about service problems and recoveries. Values: $0 = \text{don't send}$ notifications, $1 = \text{send notifications}$ .
host_notification_period	This directive is used to specify the short name of the <u>time period</u> during which the contact can be notified about host problems or recoveries. You can think of this as an "on call" time for host notifications for the contact. Read the documentation on <u>time periods</u> for more information on how this works and potential problems that may result from improper use.
service_notification_period	This directive is used to specify the short name of the <u>time period</u> during which the contact can be notified about service problems or recoveries. You can think of this as an "on call" time for service notifications for the contact. Read the documentation on <u>time periods</u> for more information on how this works and potential problems that may result from improper use.
host_notification_commands	This directive is used to define a list of the <i>short names</i> of the <u>commands</u> used to notify the contact of a <i>host</i> problem or recovery. Multiple notification commands should be separated by commas. All notification commands are executed when the contact needs to be notified. The maximum amount of time that a notification command can run is controlled by the <u>notification_timeout</u> option.
host_notification_options	This directive is used to define the host states for which notifications can be sent out to this contact. Valid options are a combination of one or more of the following: $\mathbf{d} =$ notify on DOWN host states, $\mathbf{u} =$ notify on UNREACHABLE host states, $\mathbf{r} =$ notify on host recoveries (UP states), $\mathbf{f} =$ notify when the host starts and stops <u>flapping</u> , and

	s = send notifications when host or service <u>scheduled downtime</u> starts and ends. If you specify <b>n</b> (none) as an option, the contact will not receive any type of host notifications.
service_notification_options	This directive is used to define the service states for which notifications can be sent out to this contact. Valid options are a combination of one or more of the following: $\mathbf{w}$ = notify on WARNING service states, $\mathbf{u}$ = notify on UNKNOWN service states, $\mathbf{c}$ = notify on CRITICAL service states, $\mathbf{r}$ = notify on service recoveries (OK states), and $\mathbf{f}$ = notify when the service starts and stops <u>flapping</u> . If you specify $\mathbf{n}$ (none) as an option, the contact will not receive any type of service notifications.
service_notification_commands	This directive is used to define a list of the <i>short names</i> of the <u>commands</u> used to notify the contact of a <i>service</i> problem or recovery. Multiple notification commands should be separated by commas. All notification commands are executed when the contact needs to be notified. The maximum amount of time that a notification command can run is controlled by the <u>notification_timeout</u> option.
email	This directive is used to define an email address for the contact. Depending on how you configure your notification commands, it can be used to send out an alert email to the contact. Under the right circumstances, the \$CONTACTEMAIL\$ <u>macro</u> will contain this value.
pager	This directive is used to define a pager number for the contact. It can also be an email address to a pager gateway (i.e. pagejoe@pagenet.com). Depending on how you configure your notification commands, it can be used to send out an alert page to the contact. Under the right circumstances, the \$CONTACTPAGER\$ macro will contain this value.
addressx	Address directives are used to define additional "addresses" for the contact. These addresses can be anything - cell phone numbers, instant messaging addresses, etc. Depending on how you configure your notification commands, they can be used to send out an alert to the contact. Up to six addresses can be defined using these directives ( <i>address1</i> through <i>address6</i> ). The \$CONTACTADDRESSx\$ <u>macro</u> will contain this value.
can_submit_commands	This directive is used to determine whether or not the contact can submit <u>external</u> <u>commands</u> to Nagios from the CGIs. Values: $0 = \text{don't}$ allow contact to submit commands, $1 = \text{allow}$ contact to submit commands.
retain_status_information	This directive is used to determine whether or not status-related information about the contact is retained across program restarts. This is only useful if you have enabled state retention using the <u>retain_state_information</u> directive. Value: $0 =$ disable status information retention, $1 =$ enable status information retention.
retain_nonstatus_information	This directive is used to determine whether or not non-status information about the contact is retained across program restarts. This is only useful if you have enabled state retention using the <u>retain_state_information</u> directive. Value: $0 =$ disable non-status information retention, $1 =$ enable non-status information retention.

## **Contact Group Definition**

#### **Definition Format**

Note: Directives followed by a \* are required.

# define contactgroup{

```
contactgroup_name*
alias*
members
contactgroup_members
}
```

contactgroup\_name alias contacts contactgroups

```
define contactgroup{
    contactgroup_name novell-admins
    alias Novell Administrators
    members jdoe,rtobert,tzach
}
```

### **Directive Descriptions**

contactgroup_name	This directive is a short name used to identify the contact group.
alias	This directive is used to define a longer name or description used to identify the contact group.
members	This optional directive is used to define a list of the <i>short names</i> of <u>contacts</u> that should be included in this group. Multiple contact names should be separated by commas. This directive may be used as an alternative to (or in addition to) using the <i>contactgroups</i> directive in <u>contact</u> definitions.
contactgroup_members	This optional directive can be used to include contacts from other "sub" contact groups in this contact group. Specify a comma-delimited list of short names of other contact groups whose members should be included in this group.

## **Time Period Definition**

#### **Definition Format**

Note: Directives followed by a \* are required.

define timeperiod{

timeperiod_name*	timeperiod_name
alias*	alias
[weekday]	timeranges
[exception]	timeranges
exclude	[timeperiod1,timeperiod2,,timeperiodn]
}	

#### **Example Definitions**

define timeperiod{				
timeperiod name	nonworkhours			
alias	Non-Work Hours			
sunday	00:00-24:00	;	Every	Sunday of every week
monday	00:00-09:00,17:00-24:00	;	Every	Monday of every week
tuesday	00:00-09:00,17:00-24:00	;	Every	Tuesday of every week
wednesday	00:00-09:00,17:00-24:00	;	Every	Wednesday of every week
thursday	00:00-09:00,17:00-24:00	;	Every	Thursday of every week
friday	00:00-09:00,17:00-24:00	;	Every	Friday of every week
saturday	00:00-24:00	;	Every	Saturday of every week
}				

timeperiod_name	This directives is the short name used to identify the time period.
alias	This directive is a longer name or description used to identify the time period.
	The weekday directives (" <i>sunday</i> " through " <i>saturday</i> ")are comma-delimited lists of time ranges that are "valid" times for a particular day of the week. Notice that there are seven different days for which you can define time ranges (Sunday through Saturday). Each time range is in the form of <b>HH:MM-HH:MM</b> , where hours are specified on a 24 hour clock. For example, <b>00:15-24:00</b>

	means 12:15am in the morning for this day until 12:00am midnight (a 23 hour, 45 minute total time range). If you wish to exclude an entire day from the timeperiod, simply do not include it in the timeperiod definition.
[exception]	You can specify several different types of exceptions to the standard rotating weekday schedule. Exceptions can take a number of different forms including single days of a specific or generic month, single weekdays in a month, or single calendar dates. You can also specify a range of days/dates and even specify skip intervals to obtain functionality described by "every 3 days between these dates". Rather than list all the possible formats for exception strings, I'll let you look at the example timeperiod definitions above to see what's possible. :-) Weekdays and different types of exceptions all have different levels of precedence, so its important to understand how they can affect each other. More information on this can be found in the documentation on <u>timeperiods</u> .
exclude	This directive is used to specify the short names of other timeperiod definitions whose time ranges should be excluded from this timeperiod. Multiple timeperiod names should be separated with a comma.

## **Command Definition**

#### **Definition Format**

Note: Directives followed by a \* are required.

define command {	
command_name*	command_name
command_line*	command_line
}	

### Example Definition

```
define command{
    command_name check_pop
    command_line /usr/local/nagios/libexec/check_pop -H $HOSTADDRESS$
  }
```

command_name	This directive is the short name used to identify the command. It is referenced in <u>contact</u> , <u>host</u> , and <u>service</u> definitions (in notification, check, and event handler directives), among other places.
command_line	This directive is used to define what is actually executed by Nagios when the command is used for service or host checks, notifications, or <u>event handlers</u> . Before the command line is executed, all valid <u>macros</u> are replaced with their respective values. See the documentation on macros for determining when you can use different macros. Note that the command line is <i>not</i> surrounded in quotes. Also, if you want to pass a dollar sign (\$) on the command line, you have to escape it with another dollar sign.
	<b>NOTE</b> : You may not include a <b>semicolon</b> (;) in the <i>command_line</i> directive, because everything after it will be ignored as a config file comment. You can work around this limitation by setting one of the <b>\$USER\$</b> macros in your resource file to a semicolon and then referencing the appropriate \$USER\$ macro in the <i>command_line</i> directive in place of the semicolon. If you want to pass arguments to commands during runtime, you can use <b>\$ARGn\$ macros</b> in the <i>command_line</i> directive of the command definition and then separate individual arguments from the command name (and from each other) using bang (!) characters in the object definition directive (host check command, service event handler command, etc) that references the command. More information on how arguments in command definitions are processed during runtime can be found in the documentation on <u>macros</u> .

## **Service Dependency Definition**

#### **Definition Format**

Note: Directives followed by a \* are required. However, you must supply at least one type of criteria for the definition to be of much use.

define servicedependency{

dependent_host_name*	host_name
dependent_hostgroup_name	hostgroup_name
dependent_service_description*	service_description
host_name*	host_name
hostgroup_name	hostgroup_name
service_description*	service_description
inherits_parent	[0/1]
execution_failure_criteria	[o,w,u,c,p,n]
notification_failure_criteria	[o,w,u,c,p,n]
dependency_period	timeperiod_name
}	

### Example Definition

define servicedependency{	
host_name	WWW1
service_description	Apache Web Server
dependent_host_name	WWW1
dependent_service_description	Main Web Site
execution_failure_criteria	n
notification_failure_criteria	w,u,C
}	

dependent_host_name	This directive is used to identify the <i>short name(s)</i> of the <u>host(s)</u> that the <i>dependent</i> service "runs" on or is associated with. Multiple hosts should be separated by commas. Leaving this directive blank can be used to create <u>"same host" dependencies</u> .
dependent_hostgroup_name	This directive is used to specify the <i>short name(s)</i> of the <u>hostgroup(s)</u> that the <i>dependent</i> service "runs" on or is associated with. Multiple hostgroups should be separated by commas. The dependent_hostgroup may be used instead of, or in addition to, the dependent_host directive.
dependent_service_description	This directive is used to identify the <i>description</i> of the <i>dependent</i> <u>service</u> .
host_name	This directive is used to identify the <i>short name(s)</i> of the <u>host(s)</u> that the service <i>that is being depended upon</i> (also referred to as the master service) "runs" on or is associated with. Multiple hosts should be separated by commas.
hostgroup_name	This directive is used to identify the <i>short name(s)</i> of the <u>hostgroup(s)</u> that the service <i>that is being depended upon</i> (also referred to as the master service) "runs" on or is associated with. Multiple hostgroups should be separated by commas. The hostgroup_name may be used instead of, or in addition to, the host_name directive.
service_description	This directive is used to identify the <i>description</i> of the <u>service</u> <i>that is being depended upon</i> (also referred to as the master service).
inherits_parent	This directive indicates whether or not the dependency inherits dependencies of the service <i>that is being depended upon</i> (also referred to as the master service). In other words, if the master service is dependent upon other services and any one of those dependencies fail, this dependency will also fail.

execution_failure_criteria	This directive is used to specify the criteria that determine when the dependent service should <i>not</i> be actively checked. If the <i>master</i> service is in one of the failure states we specify, the <i>dependent</i> service will not be actively checked. Valid options are a combination of one or more of the following (multiple options are separated with commas): $\mathbf{o} = \text{fail}$ on an OK state, $\mathbf{w} = \text{fail}$ on a WARNING state, $\mathbf{u} = \text{fail}$ on an UNKNOWN state, $\mathbf{c} = \text{fail}$ on a CRITICAL state, and $\mathbf{p} = \text{fail}$ on a pending state (e.g. the service has not yet been checked). If you specify $\mathbf{n}$ (none) as an option, the execution dependency will never fail and checks of the dependent service will always be actively checked (if other conditions allow for it to be). Example: If you specify $\mathbf{o}, \mathbf{c}, \mathbf{u}$ in this field, the <i>dependent</i> service will not be actively checked if the <i>master</i> service is in either an OK, a CRITICAL, or an UNKNOWN state.
notification_failure_criteria	This directive is used to define the criteria that determine when notifications for the dependent service should <i>not</i> be sent out. If the <i>master</i> service is in one of the failure states we specify, notifications for the <i>dependent</i> service will not be sent to contacts. Valid options are a combination of one or more of the following: $\mathbf{o} = \text{fail on an OK}$ state, $\mathbf{w} = \text{fail on a WARNING state}$ , $\mathbf{u} = \text{fail on an UNKNOWN state}$ , $\mathbf{c} = \text{fail on a CRITICAL state}$ , and $\mathbf{p} = \text{fail on a pending state}$ (e.g. the service has not yet been checked). If you specify $\mathbf{n}$ (none) as an option, the notification dependency will never fail and notifications for the dependent service will always be sent out. Example: If you specify $\mathbf{w}$ in this field, the notifications for the <i>dependent</i> service will not be sent out if the <i>master</i> service is in a WARNING state.
dependency_period	This directive is used to specify the short name of the <u>time period</u> during which this dependency is valid. If this directive is not specified, the dependency is considered to be valid during all times.

## Service Escalation Definition

#### **Definition Format**

Note: Directives followed by a \* are required.

define serviceescalation{

host_name*	host_name
hostgroup_name	hostgroup_name
service_description*	service_description
contacts*	contacts
contact_groups*	contactgroup_name
first_notification*	#
last_notification*	#
notification_interval*	#
escalation_period	timeperiod_name
escalation_options	[w,u,c,r]
}	

# Example Definition

<pre>define serviceescalation{</pre>	
host_name	nt-3
service_description	Processor Load
first notification	4
last notification	0
notification interval	30
contact groups	all-nt-admins,themanagers
}	

host_name	This directive is used to identify the <i>short name(s)</i> of the $host(s)$ that the service escalation should apply to or is associated with.
hostgroup_name	This directive is used to specify the <i>short name(s)</i> of the <u>hostgroup(s)</u> that the service escalation should apply to or is associated with. Multiple hostgroups should be separated by commas. The hostgroup_name may be used instead of, or in addition to, the host_name directive.
service_description	This directive is used to identify the <i>description</i> of the <u>service</u> the escalation should apply to.
first_notification	This directive is a number that identifies the <i>first</i> notification for which this escalation is effective. For instance, if you set this value to 3, this escalation will only be used if the service is in a non-OK state long enough for a third notification to go out.
last_notification	This directive is a number that identifies the <i>last</i> notification for which this escalation is effective. For instance, if you set this value to 5, this escalation will not be used if more than five notifications are sent out for the service. Setting this value to 0 means to keep using this escalation entry forever (no matter how many notifications go out).
contacts	This is a list of the <i>short names</i> of the <u>contacts</u> that should be notified whenever there are problems (or recoveries) with this service. Multiple contacts should be separated by commas. Useful if you want notifications to go to just a few people and don't want to configure <u>contact</u> groups. You must specify at least one contact or contact group in each service escalation definition.
contact_groups	This directive is used to identify the <i>short name</i> of the <u>contact group</u> that should be notified when the service notification is escalated. Multiple contact groups should be separated by commas. You must specify at least one contact or contact group in each service escalation definition.
notification_interval	This directive is used to determine the interval at which notifications should be made while this escalation is valid. If you specify a value of 0 for the interval, Nagios will send the first notification when this escalation definition is valid, but will then prevent any more problem notifications from being sent out for the host. Notifications are sent out again until the host recovers. This is useful if you want to stop having notifications sent out after a certain amount of time. Note: If multiple escalation entries for a host overlap for one or more notification ranges, the smallest notification interval from all escalation entries is used.
escalation_period	This directive is used to specify the short name of the <u>time period</u> during which this escalation is valid. If this directive is not specified, the escalation is considered to be valid during all times.
escalation_options	This directive is used to define the criteria that determine when this service escalation is used. The escalation is used only if the service is in one of the states specified in this directive. If this directive is not specified in a service escalation, the escalation is considered to be valid during all service states. Valid options are a combination of one or more of the following: $\mathbf{r}$ = escalate on an OK (recovery) state, $\mathbf{w}$ = escalate on a WARNING state, $\mathbf{u}$ = escalate on an UNKNOWN state, and $\mathbf{c}$ = escalate on a CRITICAL state. Example: If you specify $\mathbf{w}$ in this field, the escalation will only be used if the service is in a WARNING state.

## **Host Dependency Definition**

#### **Definition Format**

Note: Directives followed by a \* are required.

define hostdependency{

dependent\_host\_name\*
dependent\_hostgroup\_name
host\_name\*
hostgroup\_name

host\_name hostgroup\_name host\_name hostgroup\_name

inherits_parent	[0/1]
execution_failure_criteria	[o,d,u,p,n]
notification_failure_criteria [o,d,u,r	
dependency_period timeperiod_1	
}	

define	hostdependency{	
	host_name	WWW1
	dependent host name	DBASE1
	notification failure criteria	d,u
	}	

dependent_host_name	This directive is used to identify the <i>short name(s)</i> of the <i>dependent</i> $host(s)$ . Multiple hosts should be separated by commas.
dependent_hostgroup_name	This directive is used to identify the <i>short name(s)</i> of the <i>dependent</i> <u>hostgroup(s)</u> . Multiple hostgroups should be separated by commas. The dependent_hostgroup_name may be used instead of, or in addition to, the dependent_host_name directive.
host_name	This directive is used to identify the <i>short name(s)</i> of the <u>host(s)</u> <i>that is being depended upon</i> (also referred to as the master host). Multiple hosts should be separated by commas.
hostgroup_name	This directive is used to identify the <i>short name(s)</i> of the <u>hostgroup(s)</u> <i>that is being depended upon</i> (also referred to as the master host). Multiple hostgroups should be separated by commas. The hostgroup_name may be used instead of, or in addition to, the host_name directive.
inherits_parent	This directive indicates whether or not the dependency inherits dependencies of the host <i>that is being depended upon</i> (also referred to as the master host). In other words, if the master host is dependent upon other hosts and any one of those dependencies fail, this dependency will also fail.
execution_failure_criteria	This directive is used to specify the criteria that determine when the dependent host should <i>not</i> be actively checked. If the <i>master</i> host is in one of the failure states we specify, the <i>dependent</i> host will not be actively checked. Valid options are a combination of one or more of the following (multiple options are separated with commas): $\mathbf{o} = \text{fail on an UP state}$ , $\mathbf{d} = \text{fail on a DOWN state}$ , $\mathbf{u} = \text{fail on an UP state}$ , and $\mathbf{p} = \text{fail on a pending state}$ (e.g. the host has not yet been checked). If you specify $\mathbf{n}$ (none) as an option, the execution dependency will never fail and the dependent host will always be actively checked (if other conditions allow for it to be). Example: If you specify $\mathbf{u}$ , $\mathbf{d}$ in this field, the <i>dependent</i> host will not be actively checked if the <i>master</i> host is in either an UNREACHABLE or DOWN state.
notification_failure_criteria	This directive is used to define the criteria that determine when notifications for the dependent host should <i>not</i> be sent out. If the <i>master</i> host is in one of the failure states we specify, notifications for the <i>dependent</i> host will not be sent to contacts. Valid options are a combination of one or more of the following: $\mathbf{o} = \text{fail}$ on an UP state, $\mathbf{d} = \text{fail}$ on a DOWN state, $\mathbf{u} = \text{fail}$ on an UNREACHABLE state, and $\mathbf{p} = \text{fail}$ on a pending state (e.g. the host has not yet been checked). If you specify $\mathbf{n}$ (none) as an option, the notification dependency will never fail and notifications for the dependent host will always be sent out. Example: If you specify $\mathbf{d}$ in this field, the notifications for the <i>dependent</i> host will not be sent out if the <i>master</i> host is in a DOWN state.
dependency_period	This directive is used to specify the short name of the <u>time period</u> during which this dependency is valid. If this directive is not specified, the dependency is considered to be valid during all times.

## **Host Escalation Definition**

#### **Definition Format**

Note: Directives followed by a \* are required.

define hostescalation {	
host_name*	host_name
hostgroup_name	hostgroup_name
contacts*	contacts
contact_groups*	contactgroup_name
first_notification*	#
last_notification*	#
notification_interval*	#
escalation_period	timeperiod_name
escalation_options	[d,u,r]
}	

### Example Definition

```
define hostescalation{
    host_name router-34
    first_notification 5
    last_notification 8
    notification_interval 60
    contact_groups all-router-admins
    }
```

host_name	This directive is used to identify the <i>short name</i> of the <u>host</u> that the escalation should apply to.
hostgroup_name	This directive is used to identify the <i>short name(s)</i> of the $hostgroup(s)$ that the escalation should apply to. Multiple hostgroups should be separated by commas. If this is used, the escalation will apply to all hosts that are members of the specified hostgroup(s).
first_notification	This directive is a number that identifies the <i>first</i> notification for which this escalation is effective. For instance, if you set this value to 3, this escalation will only be used if the host is down or unreachable long enough for a third notification to go out.
last_notification	This directive is a number that identifies the <i>last</i> notification for which this escalation is effective. For instance, if you set this value to 5, this escalation will not be used if more than five notifications are sent out for the host. Setting this value to 0 means to keep using this escalation entry forever (no matter how many notifications go out).
contacts	This is a list of the <i>short names</i> of the <u>contacts</u> that should be notified whenever there are problems (or recoveries) with this host. Multiple contacts should be separated by commas. Useful if you want notifications to go to just a few people and don't want to configure <u>contact</u> <u>groups</u> . You must specify at least one contact or contact group in each host escalation definition.
contact_groups	This directive is used to identify the <i>short name</i> of the <u>contact group</u> that should be notified when the host notification is escalated. Multiple contact groups should be separated by commas. You must specify at least one contact or contact group in each host escalation definition.
notification_interval	This directive is used to determine the interval at which notifications should be made while this escalation is valid. If you specify a value of 0 for the interval, Nagios will send the first notification when this escalation definition is valid, but will then prevent any more problem notifications from being sent out for the host. Notifications are sent out again until the host recovers. This is useful if you want to stop having notifications sent out after a certain amount

	of time. Note: If multiple escalation entries for a host overlap for one or more notification ranges, the smallest notification interval from all escalation entries is used.
escalation_period	This directive is used to specify the short name of the <u>time period</u> during which this escalation is valid. If this directive is not specified, the escalation is considered to be valid during all times.
escalation_options	This directive is used to define the criteria that determine when this host escalation is used. The escalation is used only if the host is in one of the states specified in this directive. If this directive is not specified in a host escalation, the escalation is considered to be valid during all host states. Valid options are a combination of one or more of the following: $\mathbf{r}$ = escalate on an UP (recovery) state, $\mathbf{d}$ = escalate on a DOWN state, and $\mathbf{u}$ = escalate on an UNREACHABLE state. Example: If you specify $\mathbf{d}$ in this field, the escalation will only be used if the host is in a DOWN state.

## **Extended Host Information Definition**

#### **Definition Format**

Note: Directives followed by a \* are required. However, you need to supply at least one optional variable in each definition for it to be of much use.

define hostextinfo{

host_name*	host_name
notes	note_string
notes_url	url
action_url	url
icon_image	image_file
icon_image_alt	alt_string
vrml_image	image_file
statusmap_image	image_file
2d_coords	x_coord,y_coord
3d_coords	x_coord,y_coord,z_coord
}	

#### Example Definition

```
define hostextinfo{
    host_name netware1
    notes This is the primary Netware file server
    notes_url http://localhost.localdomain/hostinfo.pl?host=netware1
    icon_image novell40.png
    icon_image novell40.png
    statusmap_image novell40.gd2
    2d_coords 100,250
    3d_coords 100.0,50.0,75.0
}
```

#### Variable Descriptions

host_name	This variable is used to identify the <i>short name</i> of the <u>host</u> which the data is associated with.
notes	This directive is used to define an optional string of notes pertaining to the host. If you specify a note here, you will see the it in the <u>extended information</u> CGI (when you are viewing information about the specified host).
notes_url	This variable is used to define an optional URL that can be used to provide more information about the host. If you specify an URL, you will see a link that says "Extra Host Notes" in the

	extended information CGI (when you are viewing information about the specified host). Any valid URL can be used. If you plan on using relative paths, the base path will the the same as what is used to access the CGIs (i.e. /cgi-bin/nagios/). This can be very useful if you want to make detailed information on the host, emergency contact methods, etc. available to other support staff.
action_url	This directive is used to define an optional URL that can be used to provide more actions to be performed on the host. If you specify an URL, you will see a link that says "Extra Host Actions" in the <u>extended information</u> CGI (when you are viewing information about the specified host). Any valid URL can be used. If you plan on using relative paths, the base path will the the same as what is used to access the CGIs (i.e. <i>/cgi-bin/nagios/</i> ).
icon_image	This variable is used to define the name of a GIF, PNG, or JPG image that should be associated with this host. This image will be displayed in the <u>status</u> and <u>extended information</u> CGIs. The image will look best if it is 40x40 pixels in size. Images for hosts are assumed to be in the <b>logos</b> / subdirectory in your HTML images directory (i.e. <i>/usr/local/nagios/share/images/logos</i> ).
icon_image_alt	This variable is used to define an optional string that is used in the ALT tag of the image specified by the <i><icon_image></icon_image></i> argument. The ALT tag is used in the <u>status</u> , <u>extended</u> <u>information</u> and <u>statusmap</u> CGIs.
vrml_image	This variable is used to define the name of a GIF, PNG, or JPG image that should be associated with this host. This image will be used as the texture map for the specified host in the <u>statuswrl</u> CGI. Unlike the image you use for the <i><icon_image></icon_image></i> variable, this one should probably <i>not</i> have any transparency. If it does, the host object will look a bit wierd. Images for hosts are assumed to be in the <b>logos</b> / subdirectory in your HTML images directory (i.e. <i>/usr/local/nagios/share/images/logos</i> ).
statusmap_image	This variable is used to define the name of an image that should be associated with this host in the statusmap CGI. You can specify a JPEG, PNG, and GIF image if you want, although I would strongly suggest using a GD2 format image, as other image formats will result in a lot of wasted CPU time when the statusmap image is generated. GD2 images can be created from PNG images by using the <b>pngtogd2</b> utility supplied with Thomas Boutell's <u>gd library</u> . The GD2 images should be created in <i>uncompressed</i> format in order to minimize CPU load when the statusmap CGI is generating the network map image. The image will look best if it is 40x40 pixels in size. You can leave these option blank if you are not using the statusmap CGI. Images for hosts are assumed to be in the <b>logos</b> / subdirectory in your HTML images directory (i.e. <i>/usr/local/nagios/share/images/logos</i> ).
2d_coords	This variable is used to define coordinates to use when drawing the host in the <u>statusmap</u> CGI. Coordinates should be given in positive integers, as they correspond to physical pixels in the generated image. The origin for drawing (0,0) is in the upper left hand corner of the image and extends in the positive x direction (to the right) along the top of the image and in the positive y direction (down) along the left hand side of the image. For reference, the size of the icons drawn is usually about 40x40 pixels (text takes a little extra space). The coordinates you specify here are for the upper left hand corner of the host icon that is drawn. Note: Don't worry about what the maximum x and y coordinates that you can use are. The CGI will automatically calculate the maximum dimensions of the image it creates based on the largest x and y coordinates you specify.
3d_coords	This variable is used to define coordinates to use when drawing the host in the <u>statuswrl</u> CGI. Coordinates can be positive or negative real numbers. The origin for drawing is (0.0,0.0,0.0). For reference, the size of the host cubes drawn is 0.5 units on each side (text takes a little more space). The coordinates you specify here are used as the center of the host cube.

# **Extended Service Information Definition**

#### **Definition Format**

Note: Directives followed by a \* are required. However, you need to supply at least one optional variable in each definition for it to be of much use.

define serviceextinfo{

host_name*	host_name
service_description*	service_description
notes	note_string
notes_url	url
action_url	url
icon_image	image_file
icon_image_alt	alt_string
}	

```
define serviceextinfo{
    host_name linux2
    service_description Log Anomalies
    notes_url http://localhost.localdomain/serviceinfo.pl
    icon_image_alt Security-Related Alerts
    }
```

#### Variable Descriptions

host_name	This directive is used to identify the <i>short name</i> of the host that the <u>service</u> is associated with.
service_description	This directive is description of the service which the data is associated with.
notes	This directive is used to define an optional string of notes pertaining to the service. If you specify a note here, you will see the it in the <u>extended information</u> CGI (when you are viewing information about the specified service).
notes_url	This directive is used to define an optional URL that can be used to provide more information about the service. If you specify an URL, you will see a link that says "Extra Service Notes" in the <u>extended information</u> CGI (when you are viewing information about the specified service). Any valid URL can be used. If you plan on using relative paths, the base path will the the same as what is used to access the CGIs (i.e. <i>/cgi-bin/nagios/</i> ). This can be very useful if you want to make detailed information on the service, emergency contact methods, etc. available to other support staff.
action_url	This directive is used to define an optional URL that can be used to provide more actions to be performed on the service. If you specify an URL, you will see a link that says "Extra Service Actions" in the <u>extended information</u> CGI (when you are viewing information about the specified service). Any valid URL can be used. If you plan on using relative paths, the base path will the the same as what is used to access the CGIs (i.e. <i>/cgi-bin/nagios/</i> ).
icon_image	This variable is used to define the name of a GIF, PNG, or JPG image that should be associated with this host. This image will be displayed in the <u>status</u> and <u>extended information</u> CGIs. The image will look best if it is 40x40 pixels in size. Images for hosts are assumed to be in the <b>logos</b> / subdirectory in your HTML images directory (i.e. <i>/usr/local/nagios/share/images/logos</i> ).
icon_image_alt	This variable is used to define an optional string that is used in the ALT tag of the image specified by the <i><icon_image></icon_image></i> argument. The ALT tag is used in the <u>status</u> , <u>extended information</u> and <u>statusmap</u> CGIs.